

Electric unit 463

FEATURES:

- Factory preset address for the locomotive is 03.
- 40 khz frequency for a smoother motor control.
- The V.4 decoder supports DCC, Motorola, DC, AC and Märklin® digital systems.
- 14, 28 or 128 selectable speed steps for DCC systems.
- Load compensation function.
- Outputs overload protection for all functions.
- Audio amplifier 2W 4 Ohms.

DECODER PARAMETERS ADJUSTING:

The V.4 Loksound decoder (32 Mbit) controls several parameters. You can find a list of the most important ones at the end of this instructions. Each parameter (CV) can be configured independently using its respective command.

DCC Systems (Lenz, Intellibox, etc.)

It is much easier to modify the parameters if you have a DCC compatible digital system or an Intellibox. Please, read the corresponding chapter in your system manual (DCC decoders programming). The V.4 Loksound decoder support any NMRA programming system.

ANALOG OPERATION

When using conventional transformer, the locomotive movement will be similar to that of a locomotive without a decoder. The locomotive will only start its running when receiving a minimum voltage between 5.5 and 6 volts, as the decoder will not work with a lower tension. Please note the following warnings: The decoder installed in your Rivarossi locomotive has been specifically adapted for this model and it should be used only in this particular model. Always disconnect the decoder from the power supply before doing any work on it.

If removing the speaker were necessary for maintenance purposes, please handle it very carefully.

Do not put any pressure on it or touch the speaker membrane.

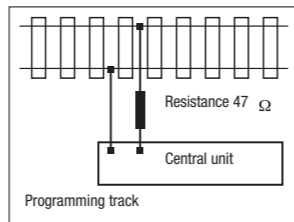
The reset function is very convenient, as you can set the original factory values again at any time. You can use this function with DCC and Motorola systems. To use this function, type "8" in CV 8 or "08" in register "08".

Adjust the sound volume.

The lokSound allows the individual volume control of each sound. Please refer to the following table to see which CV you need to change:

KEY	FUNCTION	VOLUME CVs	SOUNDSLOTS	VALUES
F0	Lights on/off			
F1	Sound on/off	1, 12, 21	259, 347, 419	115, 30, 60
F2	Short long	3	275	128
F3	Short horn	17	387	128
F4	Horn long	10	331	40
F5	Red lights			
F6	Low and high pitched horns	16	379	128
F7	Attention signal	24	443	128
F8	Doors open/close	18	395	40
F9	Curve squeal	15	371	60
F10*	Dead man's switch / stop of the locomotive	22	427	128

KEY	FUNCTION	VOLUME CVs	SOUNDSLOTS	VALUES
F11	Station announcement: Fuengirola	13	355	70
F12	Station announcement: Zambrano	11	339	70
F13	Station announcement: Nuevos Ministerios	20	411	70
F14	Station announcement: Sol	19	403	70
F15	Station announcement: Barcelona Sant	7	307	70
F16	Station announcement: Valencia	9	323	70
F17	Station announcement: Silla	4	283	70
F18	Station announcement: Oviedo	8	315	70
F19	Station announcement: Aviles	14	363	70
F20	Acceleration, Shunting Mode			
F21	Compressor	6	299	30



When programming using Lenz, Uhlenbrock or Arnold equipment, please refer to their programming instructions. If the error message "err02" is displayed during programming with Lenz or Arnold equipment, a 47 Ohm resistor (0.5 Watt or higher) must be inserted between one of the two supply cables and the programming track.

17	Extended address	Extended engine address long address of engine		192																								
18				128																								
27	Brake modus	Allowed brake modus <table border="1"> <thead> <tr> <th>Bit</th> <th>Function</th> <th>Value</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>ABC brakes, voltage higher on right side</td> <td>1</td> </tr> <tr> <td>1</td> <td>ABC brakes, voltage higher on left side</td> <td>2</td> </tr> <tr> <td>2</td> <td>ZIMO HLU brakes active</td> <td>4</td> </tr> <tr> <td>3</td> <td>Brake on DC, if polarity is vice-versa to the driving direction</td> <td>8</td> </tr> <tr> <td>4</td> <td>Brake on DC, if polarity is the same as driving direction</td> <td>16</td> </tr> </tbody> </table>	Bit	Function	Value	0	ABC brakes, voltage higher on right side	1	1	ABC brakes, voltage higher on left side	2	2	ZIMO HLU brakes active	4	3	Brake on DC, if polarity is vice-versa to the driving direction	8	4	Brake on DC, if polarity is the same as driving direction	16		28						
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28	RailCom® configuration	Settings for RailCom® <table border="1"> <thead> <tr> <th>Bit</th> <th>Function</th> <th>Value</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Channel 1 given free for address broadcast</td> <td>1</td> </tr> <tr> <td>1</td> <td>Data connection on channel 2 allowed</td> <td>2</td> </tr> <tr> <td>7</td> <td>RailCom® Plus autocratically loco registration active</td> <td>128</td> </tr> </tbody> </table>	Bit	Function	Value	0	Channel 1 given free for address broadcast	1	1	Data connection on channel 2 allowed	2	7	RailCom® Plus autocratically loco registration active	128		131												
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29	Configuration register	The most complex CV within the DCC standards. This register contains important information, which is only relevant in DCC mode. <table border="1"> <thead> <tr> <th>Bit</th> <th>Function</th> <th>Value</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Normal direction of travel. Forward becomes reverse.</td> <td>0</td> </tr> <tr> <td>1</td> <td>14 speed steps (only in DCC mode). 28 or 128 speed steps (only in DCC mode).</td> <td>0 2 Enabled</td> </tr> <tr> <td>2</td> <td>Analogue mode off. Analogue mode permitted.</td> <td>0 4 Enabled</td> </tr> <tr> <td>3</td> <td>RailCom® switched off RailCom® allowed</td> <td>0 8 Enabled</td> </tr> <tr> <td>4</td> <td>Speed curve through CV 2, 5, 6. Speed curve through CV 67 - 96V.</td> <td>0 16 Enabled</td> </tr> <tr> <td>5</td> <td>Short addresses (CV 1) in DCC-mode. Long addresses (CV 17+18) in DCC-mode</td> <td>0 32</td> </tr> </tbody> </table>	Bit	Function	Value	0	Normal direction of travel. Forward becomes reverse.	0	1	14 speed steps (only in DCC mode). 28 or 128 speed steps (only in DCC mode).	0 2 Enabled	2	Analogue mode off. Analogue mode permitted.	0 4 Enabled	3	RailCom® switched off RailCom® allowed	0 8 Enabled	4	Speed curve through CV 2, 5, 6. Speed curve through CV 67 - 96V.	0 16 Enabled	5	Short addresses (CV 1) in DCC-mode. Long addresses (CV 17+18) in DCC-mode	0 32		30			
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31	Index register H	Selection page for CV257-512	16	16																								
32	Index register L	Selection page for CV257-512	0, 2, 3	0																								
49	Extended configuration	Activate support for brake sections or switch off Back EMF control <table border="1"> <thead> <tr> <th>Bit</th> <th>Function</th> <th>Value</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Load control off Load control activated</td> <td>0 1</td> </tr> <tr> <td>1</td> <td>DC motor PWM frequency - 15 kHz pulse frequency DC motor PWM frequency - 30 kHz pulse frequency</td> <td>0 2</td> </tr> <tr> <td>2</td> <td>Märklin® delta mode - Delta mode off Märklin® delta mode - Delta mode on</td> <td>0 4</td> </tr> <tr> <td>3</td> <td>Märklin® second address off Märklin® second address on</td> <td>0 8</td> </tr> <tr> <td>4</td> <td>Automatic speed step detection DCC speed step detection off</td> <td>0 16</td> </tr> <tr> <td>5</td> <td>Disable LGB® function button mode Enable LGB® function button mode</td> <td>0 32</td> </tr> <tr> <td>6</td> <td>Disable Zimo® Manual Function Enable Zimo® Manual Function</td> <td>0 64</td> </tr> </tbody> </table>	Bit	Function	Value	0	Load control off Load control activated	0 1	1	DC motor PWM frequency - 15 kHz pulse frequency DC motor PWM frequency - 30 kHz pulse frequency	0 2	2	Märklin® delta mode - Delta mode off Märklin® delta mode - Delta mode on	0 4	3	Märklin® second address off Märklin® second address on	0 8	4	Automatic speed step detection DCC speed step detection off	0 16	5	Disable LGB® function button mode Enable LGB® function button mode	0 32	6	Disable Zimo® Manual Function Enable Zimo® Manual Function	0 64	0 - 255	155
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52	Load control parameter «K» for slow driving	"K"-component of the internal PI-controller for the low speed steps. Defines the effect of load control. The higher the value, the stronger the effect of Back EMF control.	0 - 255	60																								
53	Control Reference voltage	Defines the Back EMF voltage, which the motor should generate at maximum speed. The higher the efficiency of the motor, the higher this value may be set. If the engine does not reach maximum speed, reduce this parameter.	0 - 255	94																								
54	Load control parameter K	"K"-component of the internal PI-controller. Defines the effect of load control. The higher the value, the stronger the effect of Back EMF control.	0 - 255	48																								
55	Load control parameter I	"I"-component of the internal PI-controller. Defines the momentum (inertia) of the motor. The higher the momentum of the motor (large	1 - 255	18																								
56	Operating range of load control	0 - 100% Defines up to which speed in % load control will be active. A value of 32 indicates that load control will be effective up to half speed	1 - 192	255																								
63	Sound volume	Volume of running and additional sounds.	0-192	192																								
124	Extended Configuration #2	Additional important settings for LokSound Decoders <table border="1"> <thead> <tr> <th>Bit</th> <th>Function</th> <th>Value</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Disable driving direction Bi-directional bit: Enable driving direction when shifting direction</td> <td>0 1</td> </tr> <tr> <td>1</td> <td>Disable decoder lock with CV 15/16 Enable decoder lock with CV 15/16</td> <td>0 2</td> </tr> <tr> <td>2</td> <td>Disable serial protocol for C-Sinus Enable serial protocol for C-Sinus</td> <td>0 4</td> </tr> <tr> <td>4</td> <td>Adaptive regulation frequency Constant regulation frequency</td> <td>0 16</td> </tr> </tbody> </table>	Bit	Function	Value	0	Disable driving direction Bi-directional bit: Enable driving direction when shifting direction	0 1	1	Disable decoder lock with CV 15/16 Enable decoder lock with CV 15/16	0 2	2	Disable serial protocol for C-Sinus Enable serial protocol for C-Sinus	0 4	4	Adaptive regulation frequency Constant regulation frequency	0 16		21									
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125	Starting voltage Analog DC		0 - 255	90																								
126	Maximum speed Analog DC		0 - 255	130																								
127	Starting voltage AC		0 - 255	90																								
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The master volume control CV 63 controls all sound effects. The resulting sound volume for each individual sound effect therefore is a mixture of the master volume control settings and the individual volume control sliders.

CV	NAME	DESCRIPTION	RANGER	VALUE																											
1	Loco address.	Locomotive address	1-255	3																											
2	Start voltage.	Sets the minimum speed of the engine	1-255	2																											
3	Acceleration.	This value multiplied by 0.869 is the time from stop to maximum speed.	0-255	52 (12 seg)																											
4	Deceleration.	This value multiplied by 0.869 is the time from maximum speed to stop.	0-255	48 (11 seg)																											
5	Maximum speed.	Maximum speed of engine	0-255	255																											
6	Medium speed.	Overall engine speed	0-255	36																											
8	Manufacturer's ID.	Manufacturer's ID (ESU). Set CV8 to value 8 for automatic resetting.		151																											
13	Analogue mode F1-F8.	Status of functions F1 to F8 in analogue mode. <table border="1"> <thead> <tr> <th>Bit</th> <th>Function</th> <th>Value</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>F1</td> <td>1</td> </tr> <tr> <td>1</td> <td>F2</td> <td>2</td> </tr> <tr> <td>2</td> <td>F3</td> <td>4</td> </tr> <tr> <td>3</td> <td>F4</td> <td>8</td> </tr> <tr> <td>4</td> <td>F5</td> <td>16</td> </tr> <tr> <td>5</td> <td>F6</td> <td>32</td> </tr> <tr> <td>6</td> <td>F7</td> <td>64</td> </tr> <tr> <td>7</td> <td>F8</td> <td>128</td> </tr> </tbody> </table>	Bit	Function	Value	0	F1	1	1	F2	2	2	F3	4	3	F4	8	4	F5	16	5	F6	32	6	F7	64	7	F8	128	0-255	17
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